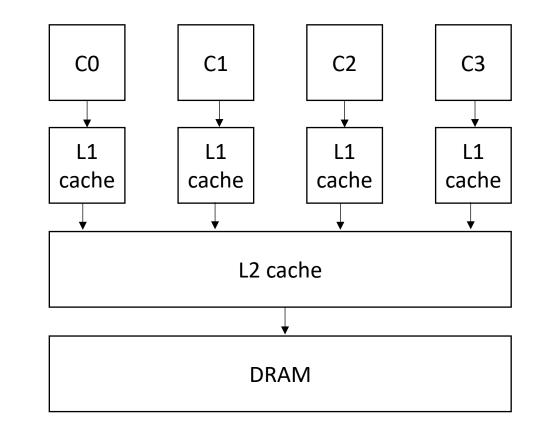
CSE211: Compiler Design Nov. 17, 2020

- Topic: SMP parallelism
 - Nesting orders
 - Reordering nestings
 - Irregular parallelism
- Discussion questions:
 - What is memory locality and why does it matter?
 - What do you do if parallel threads do not have the same amount of work?

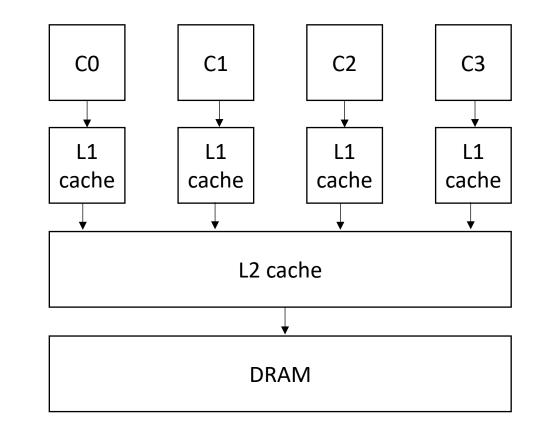


Announcements

- Midterm is out. Clarification questions are posted as discussions on Canvas. Forgot to publish...
 - Due on Thursday.
- HW3 is released. Due Dec. 4
- HW1 is graded: good job everyone!
- Paper/projects proposals due Nov. 24

CSE211: Compiler Design Nov. 17, 2020

- Topic: SMP parallelism
 - Nesting orders
 - Reordering nestings
 - Irregular parallelism
- Discussion questions:
 - What is memory locality and why does it matter?
 - What do you do if parallel threads do not have the same amount of work?



From last week:

- We want to find loops that are safe to parallelize
- Condition: outer loop iterations must be independent: they can execute in any order and provide the same result
 - using a constraint solver to detect write-write conflicts and read-write conflicts
- *new:* push/pop Z3 commands: this can save the state of the solver.

```
for (i = 0; i < 128; i++) {
    a[i%64]= a[i+64]**2;
}</pre>
```

two integers: $i_x != i_y$ $i_x >= 0$ $i_x < 128$ $i_y >= 0$ $i_y < 128$

read-write conflict check $i_x \ \% \ 64 == i_{y +} \ 64$

write-write conflict check $i_x \ 8 \ 64 == i_y \ 8 \ 64$

General formula:

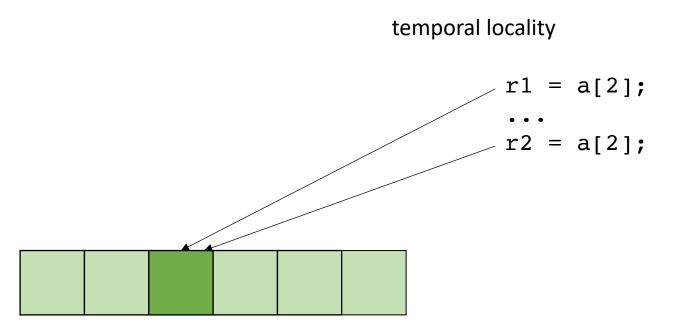
```
for (int i0 = init0; i0 < bound0(); i0++) {</pre>
    for (int i1 = init1(i0); i1 < bound1(i0); i1++) {</pre>
        . . .
        for (int iN = initN(i0, i1, ...); iN < boundN(i0, i1 ...); iN++) {</pre>
              write(a, write_index(i0, i1 .. iN))
              read(a, read index(i0, i1 .. iN));
        }
            1. Create two variables for each loop variable: i0_x, i0_y, i1_x, i1_y ...
            Set outer loop: i0_x != i0_y
            2. Constrain them to be inside their bounds:
            for w in from (0,N): iw_{x,v} \ge initw(...), iw_{x,v} \le boundN(...)
            3. Enumerate all pairs of potential write-write conflicts:
            check: write_index(i0x, i1x .. iNx) == write_index(i0y, i1y, ... iNy)
            4. Do the same for write-read conflicts
```

DOALL Loops

- These loops are called DOALL loops
- Once found, they can be passed to additional passes to fine-tune the parallelism (locality, number of threads, scheduling etc.)
- This lecture: nesting order and scheduling

• Locality is key for good parallel performance:

- Locality is key for good parallel performance:
- Two types of locality:
 - Temporal locality
 - Spatial locality

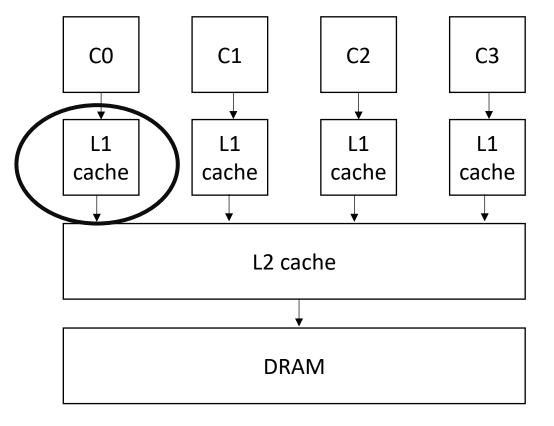


- Locality is key for good parallel performance:
- Two types of locality:
 Temporal locality
 Spatial locality
 r1 = a[2];
 r2 = a[3];

how far apart can memory locations be?

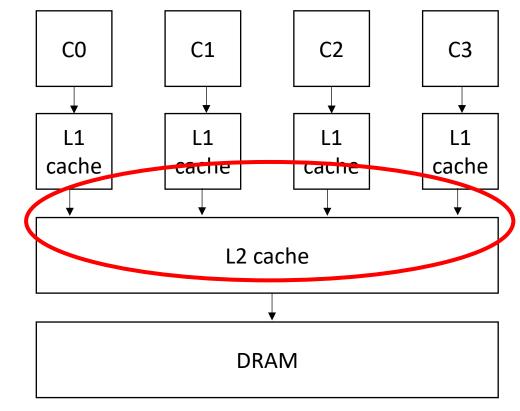
• Locality is key for good parallel performance:

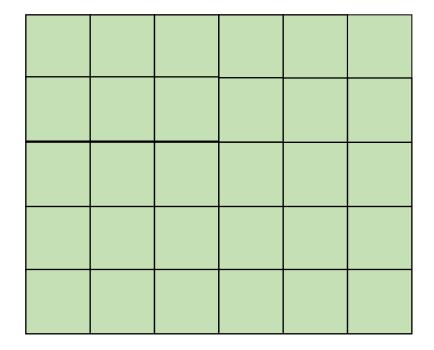
good data locality: cores will spend most of their time accessing private caches



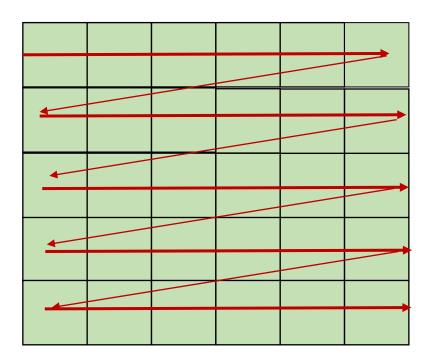
• Locality is key for good parallel performance:

Bad data locality: cores will pressure and thrash shared memory resources

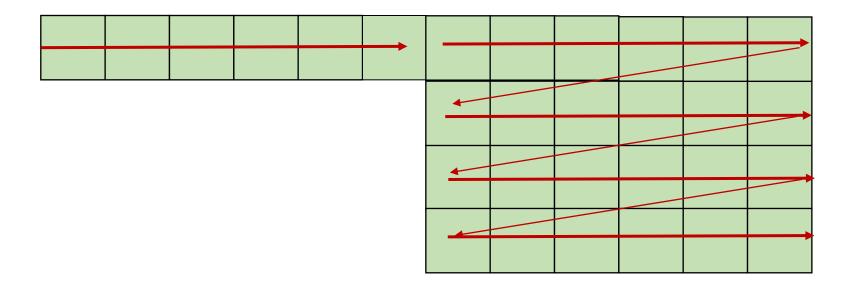




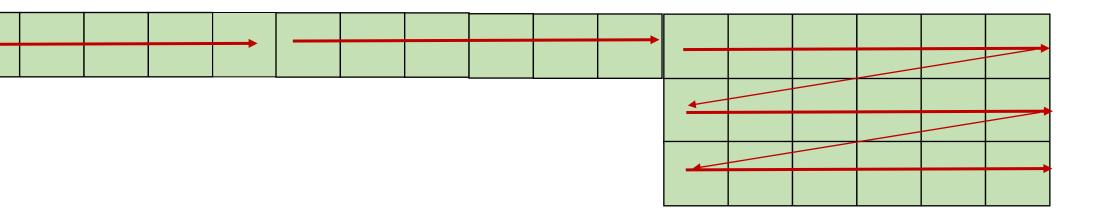
Row major



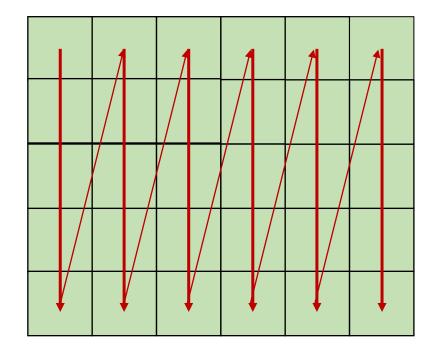
Row major



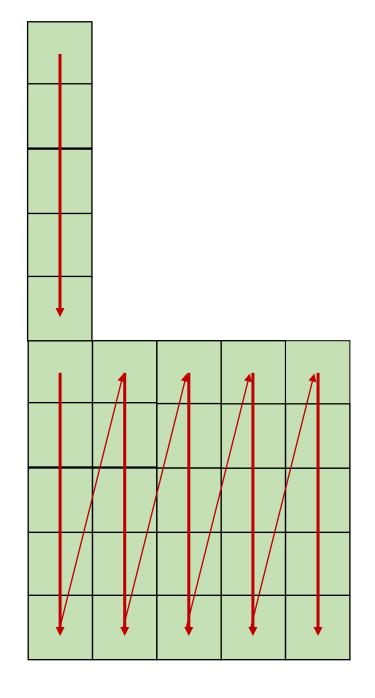
Row major



Column major? Fortran Matlab R



Column major? Fortran Matlab R



x1 = a[0,0]; x2 = a[0, 1];

good pattern for row major bad pattern for column major

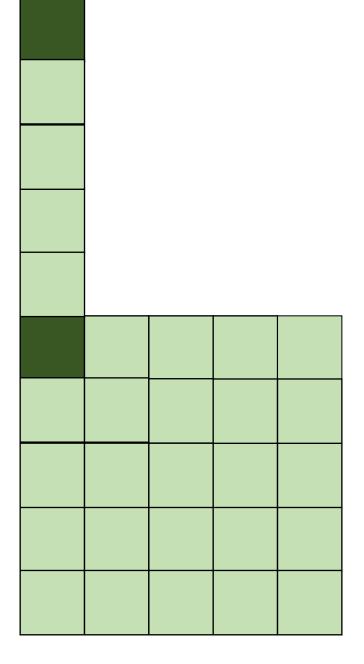
unrolled row major: still has locality

x1 = a[x,y]; x2 = a[x, y+1];

good pattern for row major bad pattern for column major

x1 = a[x,y]; x2 = a[x, y+1];

good pattern for row major bad pattern for column major unrolled column major: Bad locality



x1 = a[0,0]; x2 = a[1, 0];

good pattern for column major bad pattern for row major

row major unrolled: bad spatial locality

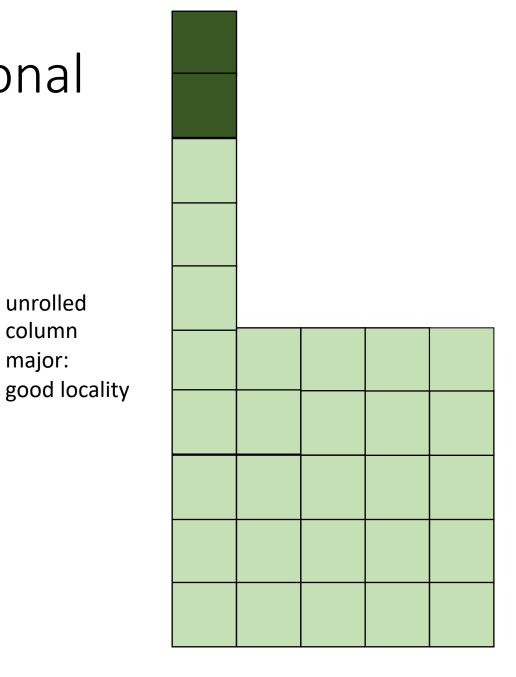
unrolled

column

major:

x1 = a[x, y]; $x^{2} = a[x+1, y];$

good pattern for column major bad pattern for row major



How much does this matter?

which will be faster? by how much?

Demo

How to reorder loop nestings?

- For a DOALL loop, if loop bounds are independent, they can simply be re-ordered.
- If they are dependent...

bad nesting order for row-major!

bad nesting order for row-major!

but iteration variables are dependent

bad nesting order for row-major!

but iteration variables are dependent

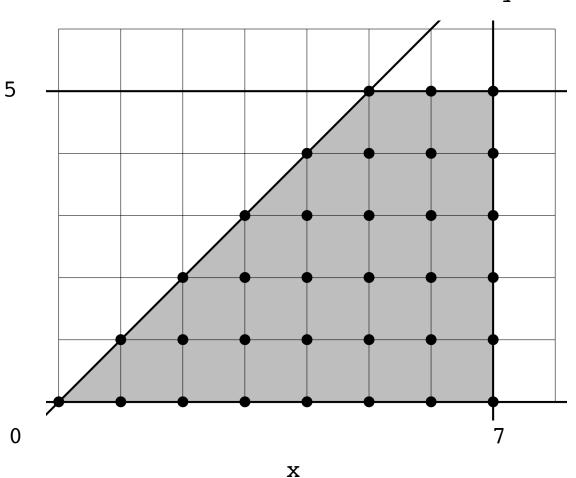
```
loop constraints
y >= 0
y <= 5
x >= y
x <= 7</pre>
```

 $\mathbf{x} = \mathbf{y}$

loop constraints
y >= 0
y <= 5
x >= y
x <= 7</pre>

У

System with N variables can be viewed as an N dimensional polyhedron



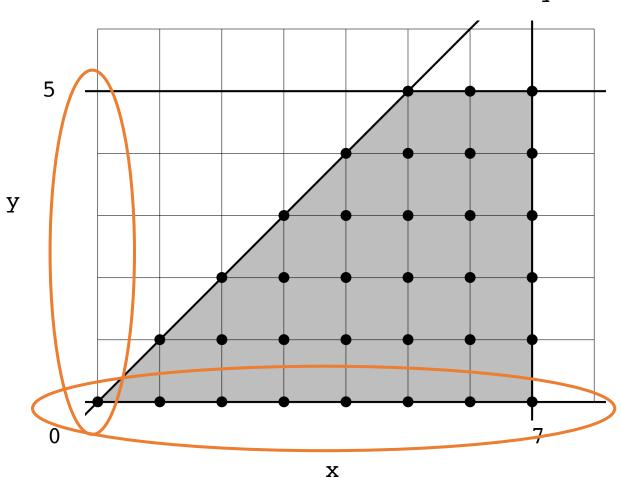
Fourier-Motzkin elimination:

- Given a system of inequalities with N variables, reduce it to a system with N 1 variables.
- A system of inequalities describes an N-dimensional polyhedron. Produce a system of equations that projects the polyhedron onto an N-1 dimensional space

x = y

loop constraints
y >= 0
y <= 5
x >= y
x <= 7</pre>

System with N variables can be viewed as an N dimensional polyhedron



Fourier-Motzkin elimination:

• To eliminate variable x_i :

For every pair of lower bound L_i and upper bound U_i on x_i , create:

 $L_i \leq x_i \leq U_i$ Then simply remove x_i :

 $L_i \leq U_i$

Example: remove y from the constraints

```
for (y = 0; y <= 5; y++) {
  for (x = y; x <= 7; x++) {
     a[x,y] = b[x,y] + c[x,y];
  }
}</pre>
```

All pairs of upper/lower bounds on y:

loop constraints

- y >= 0
- y <= 5
- x >= y
- x <= 7

0 <= y <= 5

0 <= y <= x

```
for (y = 0; y <= 5; y++) {
   for (x = y; x <= 7; x++) {
      a[x,y] = b[x,y] + c[x,y];
   }
}</pre>
```

All pairs of upper/lower bounds on y:

loop constraints

y >= 0 y <= 5 x >= y

```
for (y = 0; y <= 5; y++) {
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  }
}</pre>
```

All pairs of upper/lower bounds on y:

loop constraints
y >= 0
y <= 5
x >= y
x <= 7</pre>

 $0 \le y \le x$

0 <= y <= 5

Then eliminate y:

0 <= 5 0 <= x

```
for (y = 0; y <= 5; y++) {
  for (x = y; x <= 7; x++) {
     a[x,y] = b[x,y] + c[x,y];
  }
}</pre>
```

All pairs of upper/lower bounds on y:

loop constraints

y >= 0 y <= 5 x >= y x <= 7 $0 \le y \le 5$ $0 \le y \le x$

Then eliminate y:

<mark>0 <= 5</mark> 0 <= x

```
for (y = 0; y <= 5; y++) {
  for (x = y; x <= 7; x++) {
     a[x,y] = b[x,y] + c[x,y];
  }
}</pre>
```

All pairs of upper/lower bounds on y:

loop constraints
y >= 0
y <= 5</pre>

x >= y x <= 7 0 <= y <= x

0 <= y <= 5

Then eliminate y:

0 <= x

```
for (y = 0; y <= 5; y++) {
  for (x = y; x <= 7; x++) {
     a[x,y] = b[x,y] + c[x,y];
  }
}</pre>
```

All pairs of upper/lower bounds on y:

loop constraints $y \ge 0$

- y <= 5
- x >= y

x <= 7

 $0 \le y \le x$ Then eliminate y:

0 <= y <= 5

loop constraints without y:

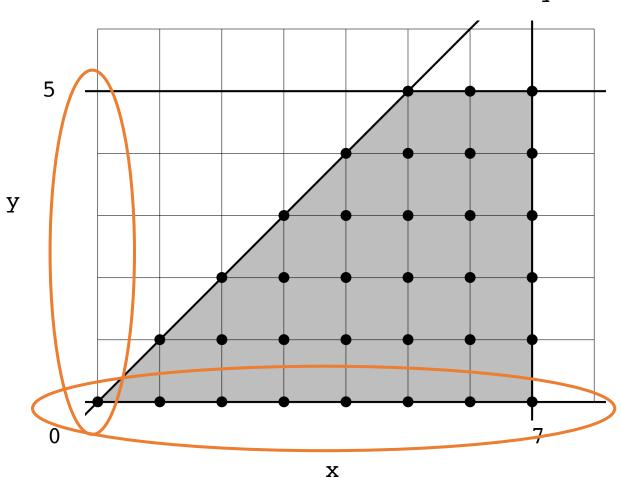
x >= 0 x <= 7

0 <= x

x = y

loop constraints
y >= 0
y <= 5
x >= y
x <= 7</pre>

System with N variables can be viewed as an N dimensional polyhedron



Reording Loop bounds:

- Given a new order: $[x_0, x_1, x_2, ..., x_n]$
- For each variable x_i : perform Fourier-Motzkin elimination to eliminate any variables that come after x_i in the new order.
- Instantiate loop conditions for x_i, potentially using max/min operators

loop constraints

y >= 0 y <= 5

x >= y

```
for (y = 0; y <= 5; y++) {
  for (x = y; x <= 7; x++) {
     a[x,y] = b[x,y] + c[x,y];
  }
}</pre>
```

new order: [x,y]

for x: eliminate y using FM elimination:

loop constraints

- y >= 0 y <= 5
- $x \ge y$

new order: [x,y]

for x: eliminate y using FM elimination:

x loop constraints without y:

x >= 0 x <= 7

loop constraints

y >= 0

y <= 5

x >= y

loop constraints

y >= 0

y <= 5

x >= y

x <= 7

new order: [x,y]

for x: eliminate y using FM elimination:

x loop constraints without y:

x >= 0 x <= 7

- y loop constraints:
- y >= 0
- y <= 5
- у <= х

new order: [x,y]

for x: eliminate y using FM elimination:

x loop constraints without y:

x >= 0 x <= 7

- y loop constraints:
- y >= 0
- <mark>y <= 5</mark>
- <mark>y <= x</mark>

- loop constraints
- y >= 0
- y <= 5
- x >= y
- x <= 7

new order: [x,y]

for x: eliminate y using FM elimination:

x loop constraints without y:

x >= 0 x <= 7

y loop constraints: y >= 0 y <= min(x,5)</pre>

loop constraints

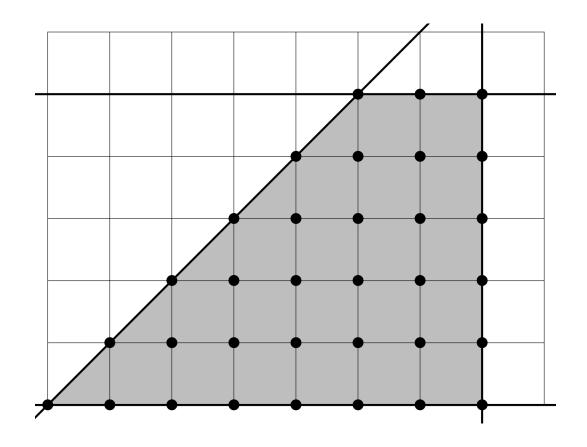
- y >= 0
- y <= 5
- x >= y
- x <= 7

У

x loop constraints without y:

x >= 0 x <= 7

y loop constraints: y >= 0 y <= min(x,5)</pre>



Х

Reordering loop bounds

- only works if loop increments by 1; assumes a closed polyhedron
- best performance when array indexes are simple:
 - e.g.: a[x,y]
 - harder with, e.g.: a[x*5+127, y+x*37]
 - There exists schemes to automatically detect locality. Reach chapter 10 of the Dragon book
- compiler implementation allows exploration and auto-tuning

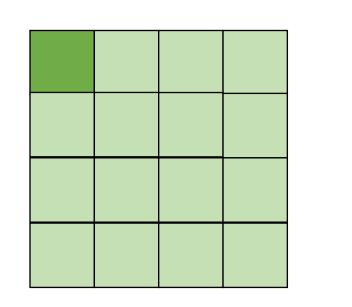
 In some cases, there might not be a good nesting order for all accesses:

 $A = B + C^T$

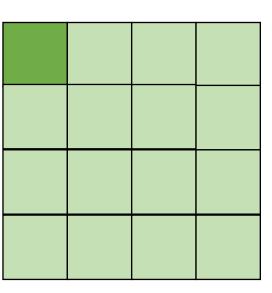
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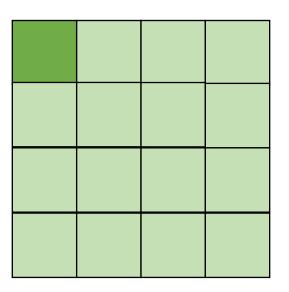
В



Α





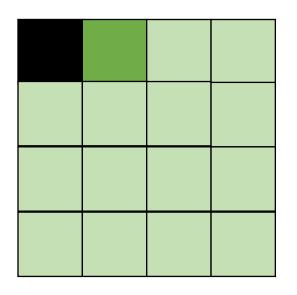


cold miss for all of them

 In some cases, there might not be a good nesting order for all accesses:

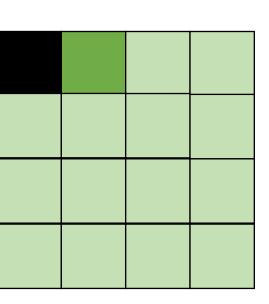
$$A = B + C^T$$

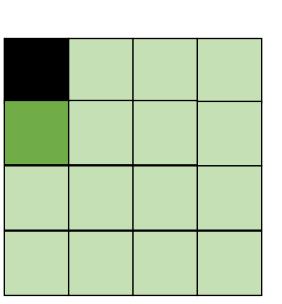
В



Hit on A and B. Miss on C

Α

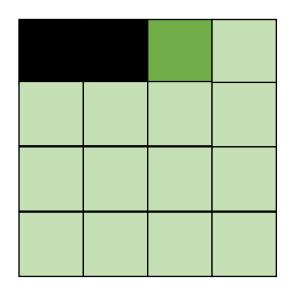




С

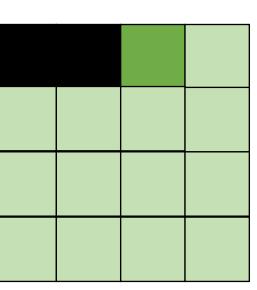
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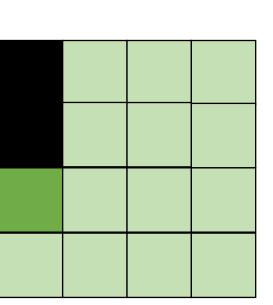
$$A = B + C^T$$



Α







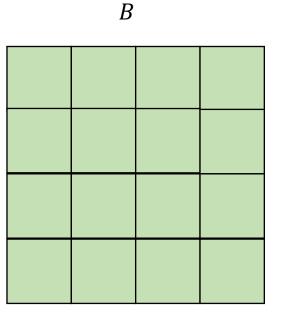
С

Hit on A and B. Miss on C

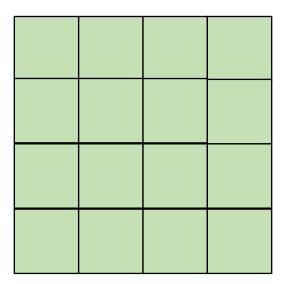
• Blocking operates on smaller chunks to exploit locality in column increment accesses. Example 2x2

A

$$A = B + C^{T}$$

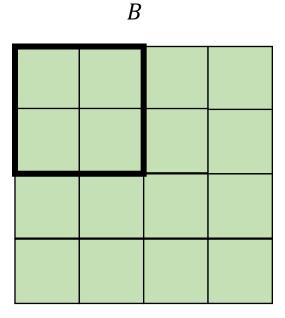




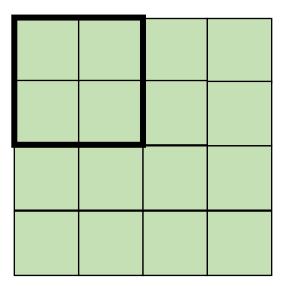


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$$A = B + C^T$$

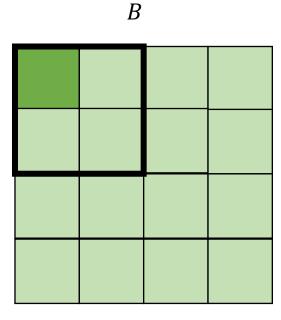




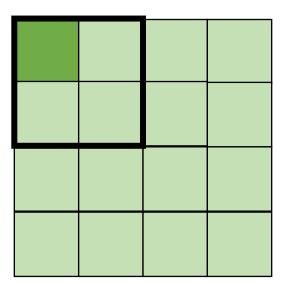


• Blocking operates on smaller chunks to exploit locality in column increment accesses. Example 2x2

 $A = B + C^T$





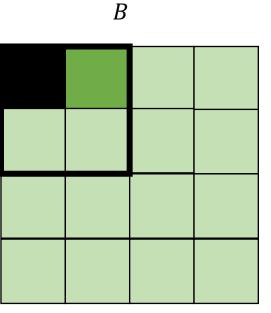


cold miss for all of them

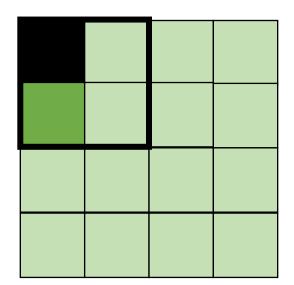
• Blocking operates on smaller chunks to exploit locality in column increment accesses. Example 2x2

A

 $A = B + C^T$



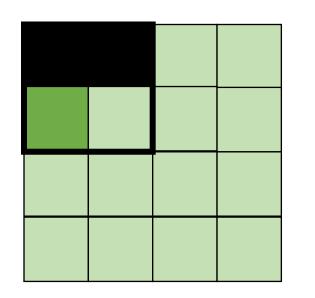
С



Miss on C

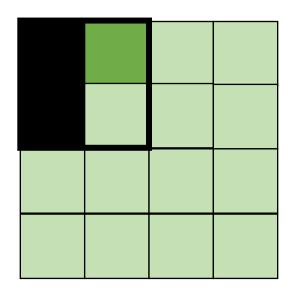
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$$A = B + C^T$$



A

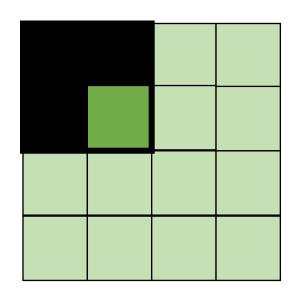




Miss on A,B, hit on C

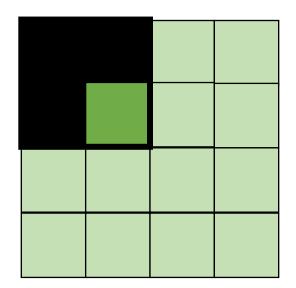
 Blocking operates on smaller chunks to exploit locality in column increment accesses. Example 2x2

$$A = B + C^T$$



Α





В

Hit on all!

• Add two outer loops for both x and y

```
for (int x = 0; x < SIZE; x++) {
    for (int y = 0; y < SIZE; y++) {
        a[x*SIZE + y] = b[x*SIZE + y] + c[y*SIZE + x];
    }
}</pre>
```

Add two outer loops for both x and y

```
for (int xx = 0; xx < SIZE; xx += B) {
  for (int yy = 0; yy < SIZE; yy += B) {
    for (int x = xx; x < xx+B; x++) {
      for (int y = yy; y < yy+B; y++) {
         a[x*SIZE + y] = b[x*SIZE + y] + c[y*SIZE + x];
      }
    }
}</pre>
```

Add two outer loops for both x and y

```
for (int xx = 0; xx < SIZE; xx += B) {
  for (int yy = 0; yy < SIZE; yy += B) {
    for (int x = xx; x < xx+B; x++) {
      for (int y = yy; y < yy+B; y++) {
        a[x*SIZE + y] = b[x*SIZE + y] + c[y*SIZE + x];
      }
    }
}</pre>
```

Add two outer loops for both x and y

```
for (int xx = 0; xx < SIZE; xx += B) {
  for (int yy = 0; yy < SIZE; yy += B) {
    for (int x = xx; x < xx+B; x++) {
      for (int y = yy; y < yy+B; y++) {
         a[x*SIZE + y] = b[x*SIZE + y] + c[y*SIZE + x];
      }
    }
}</pre>
```

Add two outer loops for both x and y

```
for (int xx = 0; xx < SIZE; xx += B) {
  for (int yy = 0; yy < SIZE; yy += B) {
    for (int x = xx; x < xx+B; x++) {
      for (int y = yy; y < yy+B; y++) {
        a[x*SIZE + y] = b[x*SIZE + y] + c[y*SIZE + x];
      }
    }
}</pre>
```

Demo

Moving on...

- Independent iterations have different amount of work to compute
- Threads with longer tasks take longer to compute.
- Threads with shorter tasks are underutilized.

- Independent iterations have different amount of work to compute
- Threads with longer tasks take longer to compute.
- Threads with shorter tasks are under utilized.

```
for (x = 0; x < SIZE; x++) {
  for (y = 0; y < SIZE; y++) {
    a[x,y] = b[x,y] + c[x,y];
  }
}</pre>
```

example: regular (or embarrassingly) parallelism: each x iteration performs the same amount of work

- Independent iterations have different amount of work to compute
- Threads with longer tasks take longer to compute.
- Threads with shorter tasks are under utilized.

```
for (x = 0; x < SIZE; x++) {
   for (y = x; y < SIZE; y++) {
      a[x,y] = b[x,y] + c[x,y];
   }
}</pre>
```

irregular (or unbalanced) parallelism: each x iteration performs different amount of work.

- Calculate imbalance cost if x is chunked:
 - Thread 1 takes iterations 0 SIZE/2
 - Thread 2 takes iterations SIZE/2 SIZE

```
for (x = 0; x < SIZE; x++) {
  for (y = x; y < SIZE; y++) {
     a[x,y] = b[x,y] + c[x,y];
  }
}</pre>
```

- Calculate imbalance cost if x is chunked:
 - Thread 1 takes iterations 0 SIZE/2
 - Thread 2 takes iterations SIZE/2 SIZE

```
Calculate how much total work:
```

total_work =
$$\sum_{n=0}^{SIZE} n$$

```
for (x = 0; x < SIZE; x++) {
   for (y = x; y < SIZE; y++) {
      a[x,y] = b[x,y] + c[x,y];
   }
}</pre>
```

Irregular parallelism in loops

- Calculate imbalance cost if x is chunked:
 - Thread 1 takes iterations 0 SIZE/2
 - Thread 2 takes iterations SIZE/2 SIZE

```
Calculate how much total work:
```

total_work =
$$\sum_{n=0}^{SIZE} n$$

Calculate work done by second thread:

```
for (x = 0; x < SIZE; x++) {
   for (y = x; y < SIZE; y++) {
      a[x,y] = b[x,y] + c[x,y];
   }
}</pre>
```

$$t2_work = \sum_{n=0}^{SIZE/2} n$$

Irregular parallelism in loops

- Calculate imbalance cost if x is chunked:
 - Thread 1 takes iterations 0 SIZE/2
 - Thread 2 takes iterations SIZE/2 SIZE

```
SIZE
```

Calculate how much total work:

total_work =
$$\sum_{n=0}^{NLL} n$$

Calculate work done by second thread:

```
for (x = 0; x < SIZE; x++) {
   for (y = x; y < SIZE; y++) {
      a[x,y] = b[x,y] + c[x,y];
   }
}</pre>
```

$$t2_work = \sum_{n=0}^{SIZE/2} n$$

Calculate work work done by first thread:

t1_work = total_work - t2_work

Irregular parallelism in loops

Calculate how much total work:

total_work =
$$\sum_{n=0}^{SIZE} n$$

Calculate work done by second thread:

$$t2_work = \sum_{n=0}^{SIZE/2} n$$

Calculate work work done by first thread:

t1_work = total_work - t2_work

Example: SIZE = 64

total_work = 2016 t2_work = 496 t1_work = 1520

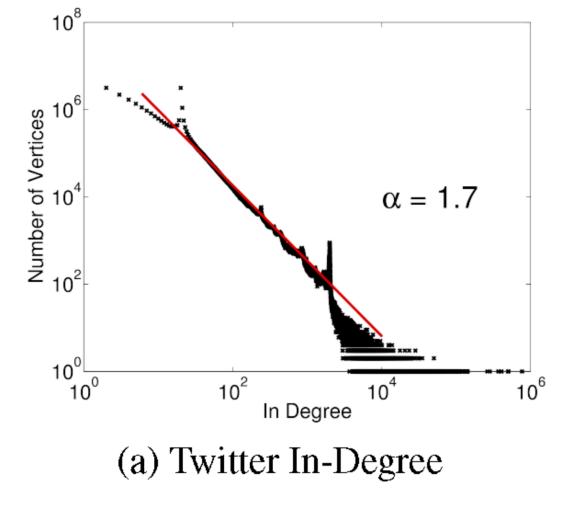
t1 does ~3x more work than t2

Only provides ~1.3x speedup

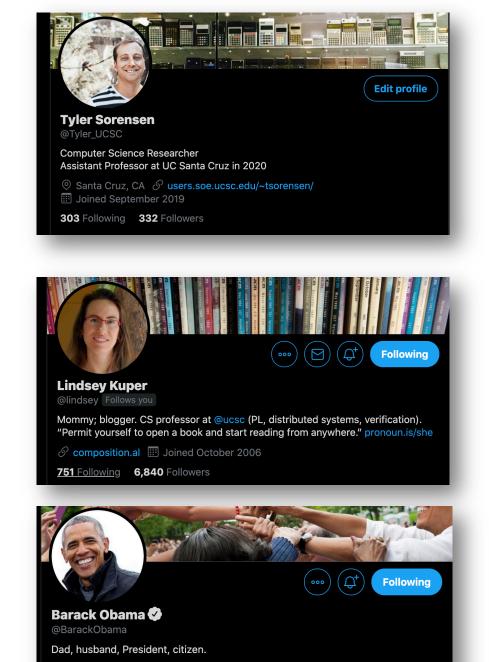
Potential solution: Have T1 do only ¼ of the iterations Gives a better speedup of 1.77x

Not a feasible solution because often times load imbalance is not given by a static equation on loop bounds!

Where does irregular parallelism show up?

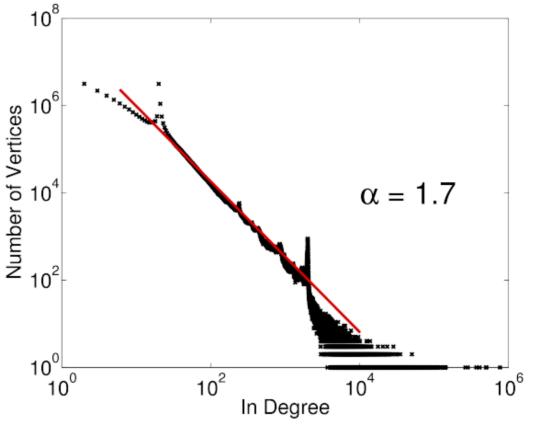


from "PowerGraph: Distributed Graph-Parallel Computation on Natural Graphs", OSDI 2012



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(a) Twitter In-Degree

from "PowerGraph: Distributed Graph-Parallel Computation on Natural Graphs", OSDI 2012

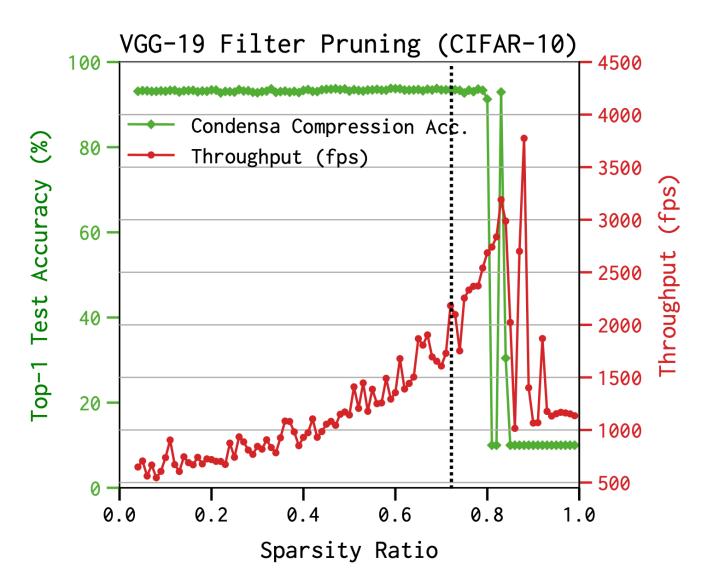


- Vertex programming model iterates over each node in parallel.
- Each node pulls in values from neighbors
- Similar to flow analysis!



Sparse Neural Nets

from: "A PROGRAMMABLE APPROACH TO MODEL COMPRESSION". arxiv 2019.



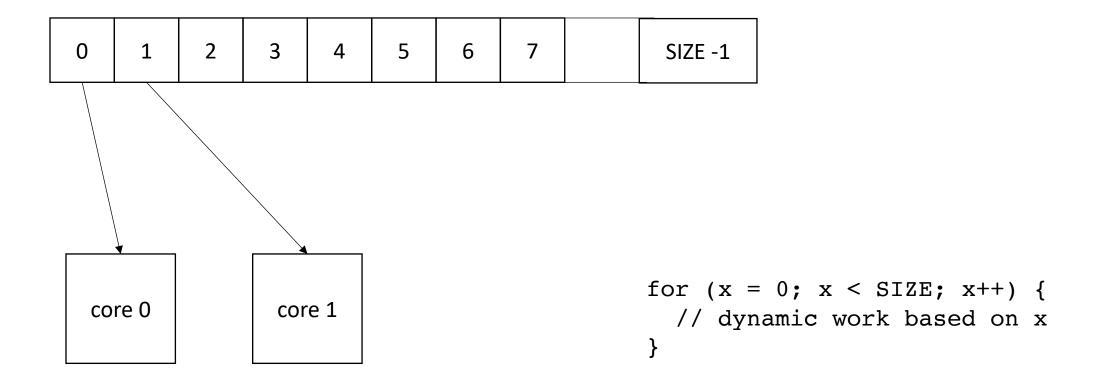
How can we deal with load imbalance?

• Great research question! Changes per domain/architecture/input etc.

- Threads dynamically get assigned to loop iterations
- Two approaches:
 - global (pessimistic)
 - local (optimistic)

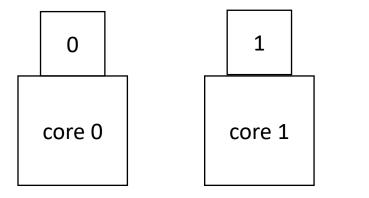
0	1	2	3	4	5	6	7		SIZE -1	
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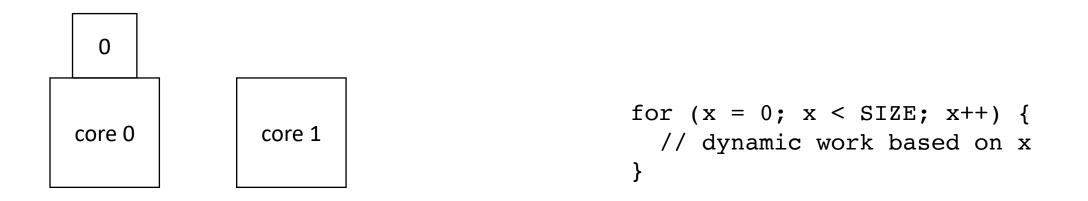
• Global worklist: threads take tasks (iterations) dynamically

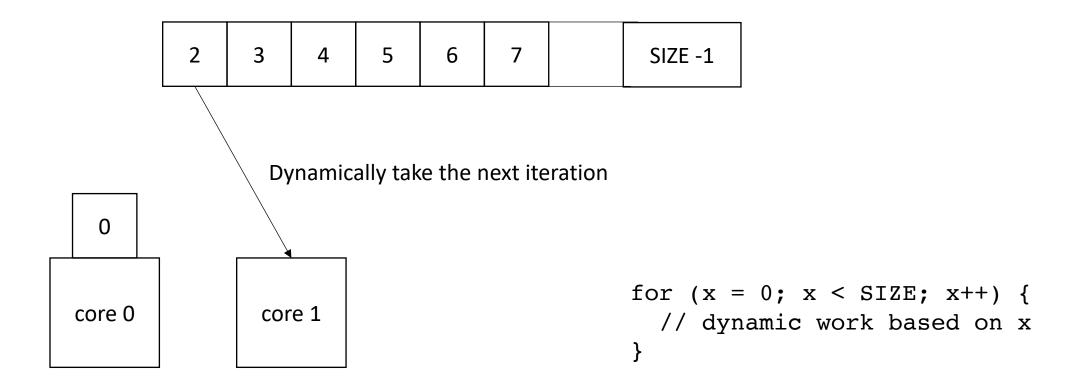
2	3	4	5	6	7		SIZE -1
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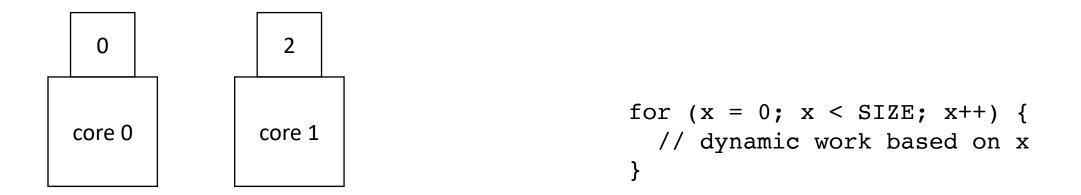
for (x = 0; x < SIZE; x++) {
 // dynamic work based on x
}</pre>

2	3	4	5	6	7		SIZE -1
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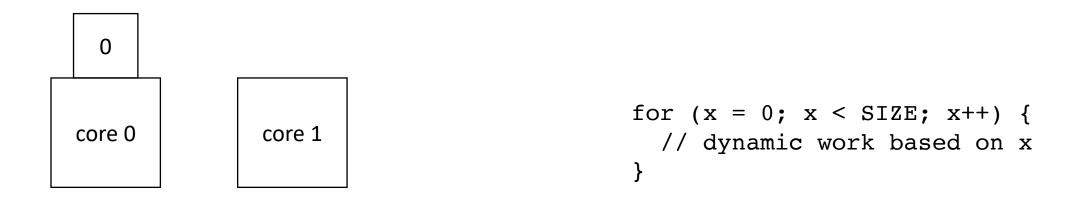




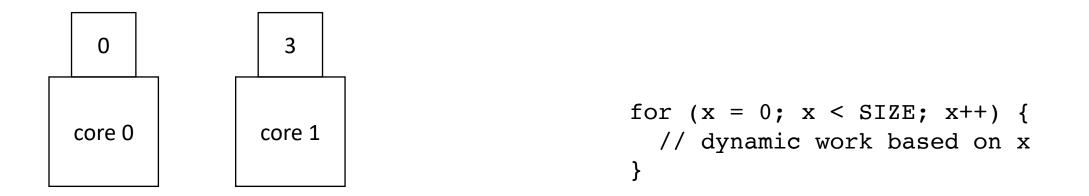
3	4	5	6	7		SIZE -1
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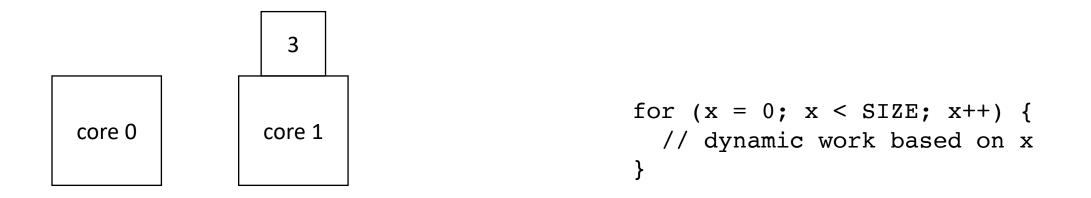
3	4	5	6	7		SIZE -1
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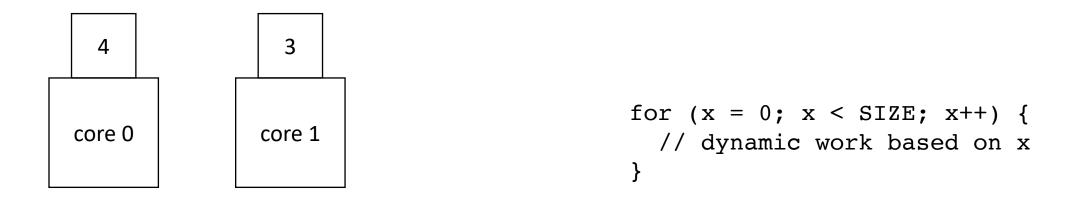
4	5	6	7		SIZE -1
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4	5	6	7		SIZE -1
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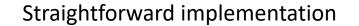


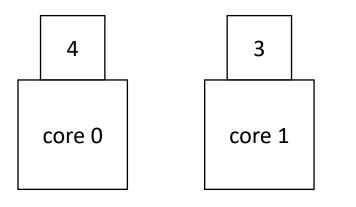
5 6	7		SIZE -1
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• Global worklist: threads take tasks (iterations) dynamically

5	6	7		SIZE -1
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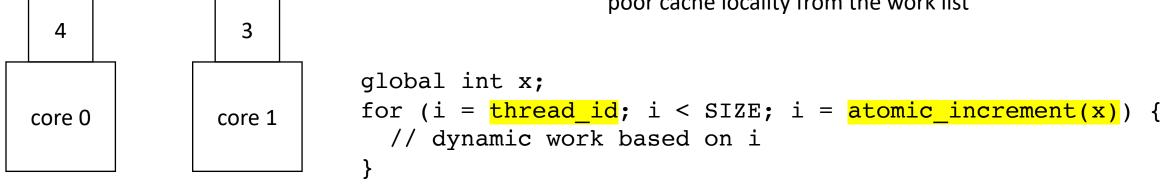


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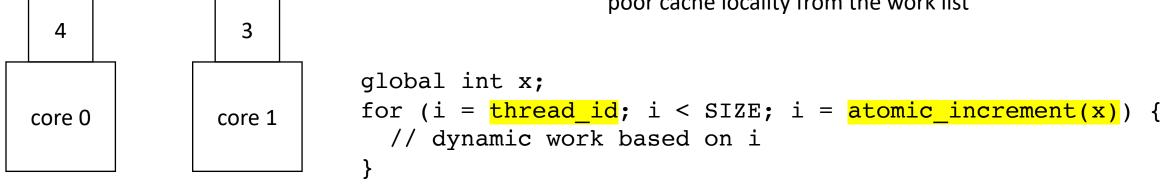
Straightforward implementation downsides: contentious atomic operation for every task poor cache locality from the work list



• Global worklist: threads take tasks (iterations) dynamically

5	6	7		SIZE -1
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Straightforward implementation downsides: contentious atomic operation for every task poor cache locality from the work list

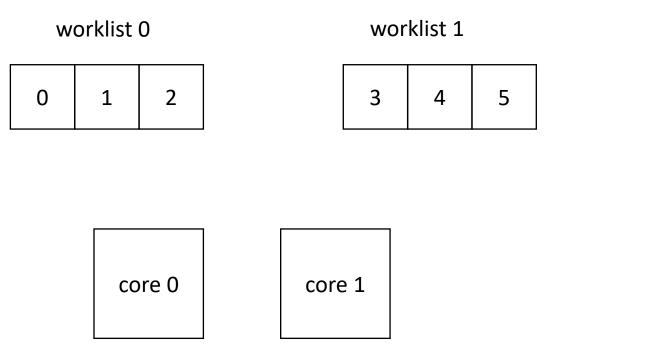


 Local worklists: threads optimistically are assigned an even sized chunk of work. Threads that finish early steal from unfinished threads

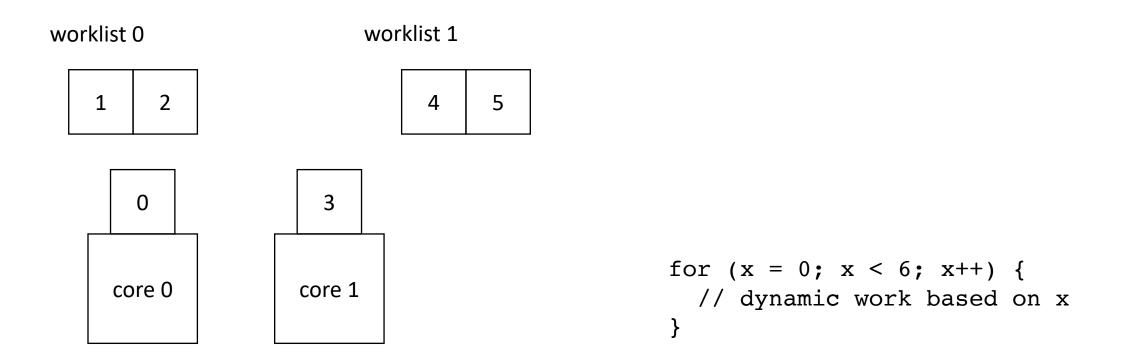
0	1	2	3	4	5
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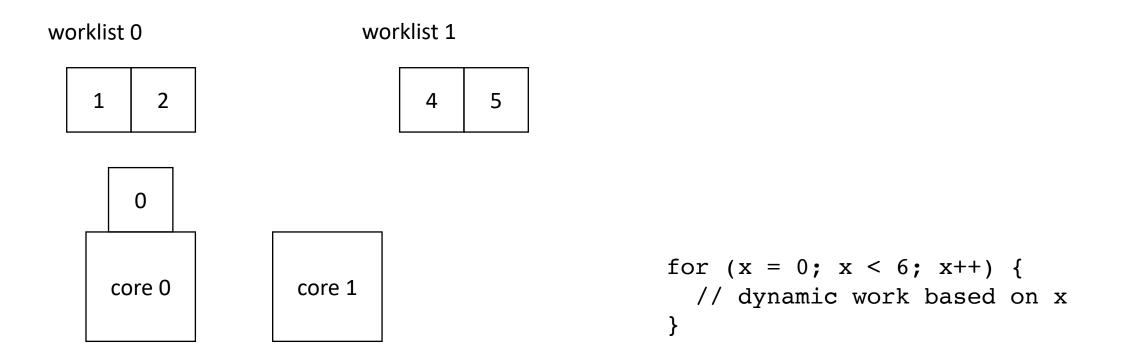


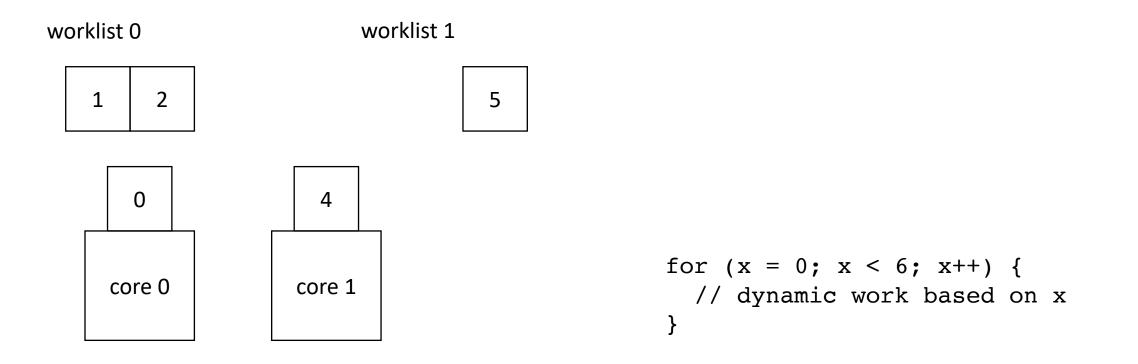
• local worklists: divide tasks into different worklists for each thread

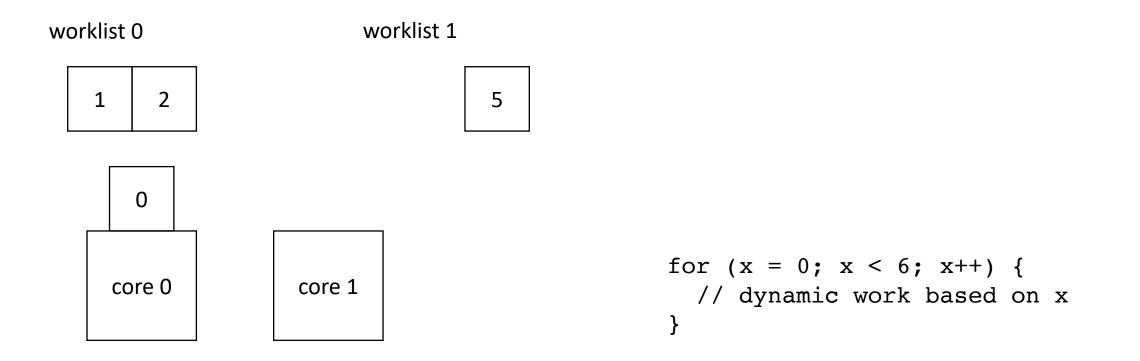


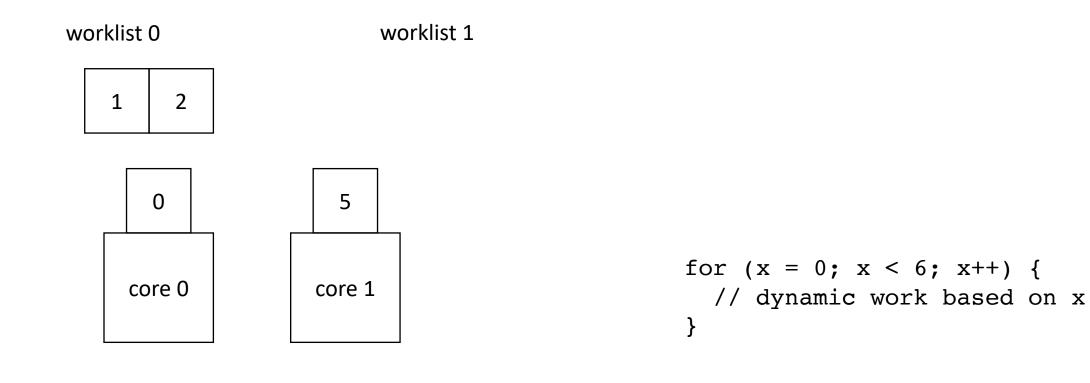
for (x = 0; x < 6; x++) {
 // dynamic work based on x
}</pre>

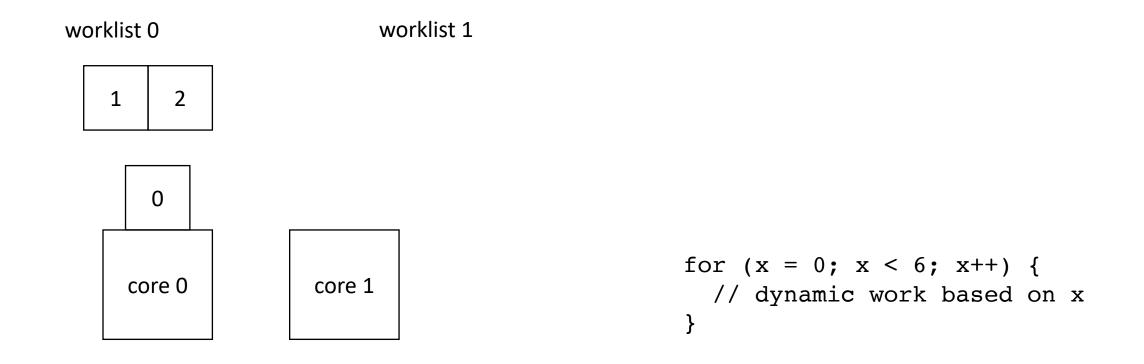


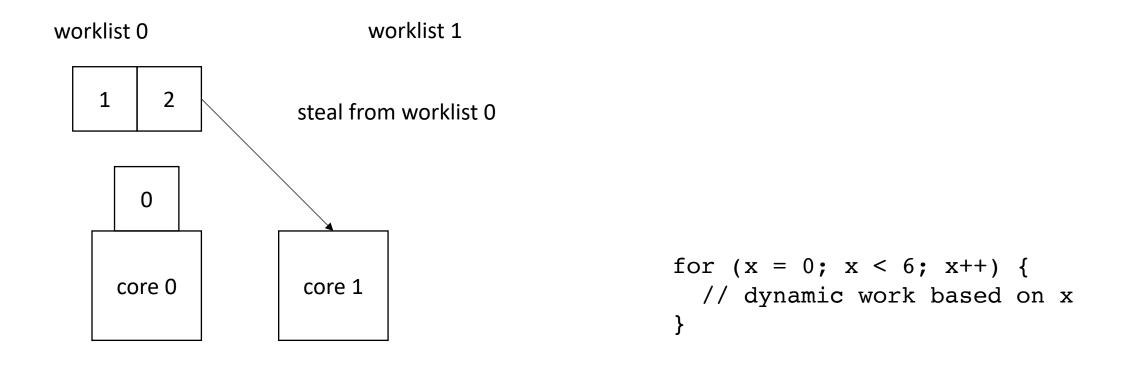


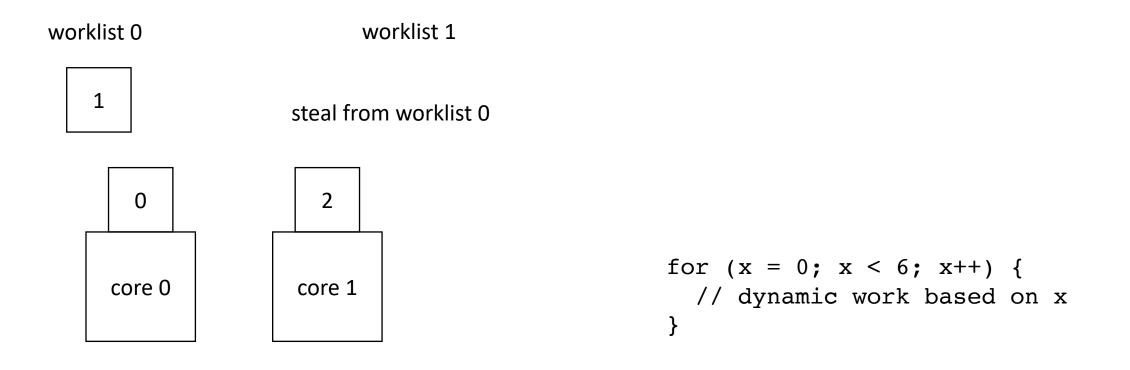




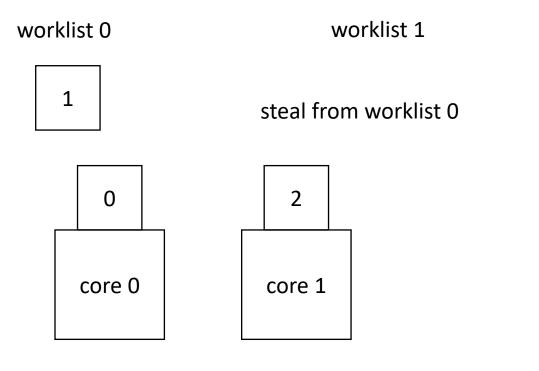








• local worklists: divide tasks into different worklists for each thread



Implementation more difficult. Requires efficient concurrent data-structures, stealing strategies, etc.

Pros: less contention, better cache locality

for (x = 0; x < 6; x++) {
 // dynamic work based on x
}</pre>

- Well-studied, available (e.g. OpenMP)
- Requires fine-grained synchronization (concurrent data-structures, or atomic read-modify-write)
- Demo

Next class:

- Inspect/Execute load balancing
- Decoupled Access Execute