8,192-word × 8-bit High Speed CMOS Static RAM

HITACHI

ADE-203-492A (Z) Rev. 1.0 Sep. 5, 1996

Description

The Hitachi HM6264BI is 64k-bit static RAM organized 8-kword \times 8-bit. It realizes higher performance and low power consumption by 1.5 μ m CMOS process technology. The device, packaged in 450 mil SOP (foot print pitch width), 600 mil plastic DIP, is available for high density mounting.

Features

• High speed

— Fast access time: 100/120 ns (max)

• Low power

— Standby: 10 μW (typ)

— Operation: 15 mW (typ) (f = 1 MHz)

• Single 5 V supply

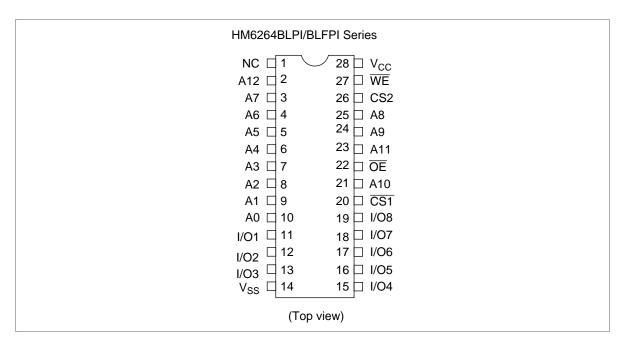
• Completely static memory

- No clock or timing strobe required
- Equal access and cycle times
- Common data input and output
 - Three state output
- Directly TTL compatible
 - All inputs and outputs
- · Battery backup operation capability
- Operating temperature range
 - -40° C to $+85^{\circ}$ C

Ordering Information

Type No.	Access time	Package
HM6264BLPI-10 HM6264BLPI-12	100 ns 120 ns	600-mil, 28-pin plastic DIP (DP-28)
HM6264BLFPI-10T HM6264BLFPI-12T	100 ns 120 ns	450-mil, 28-pin plastic SOP(FP-28DA)

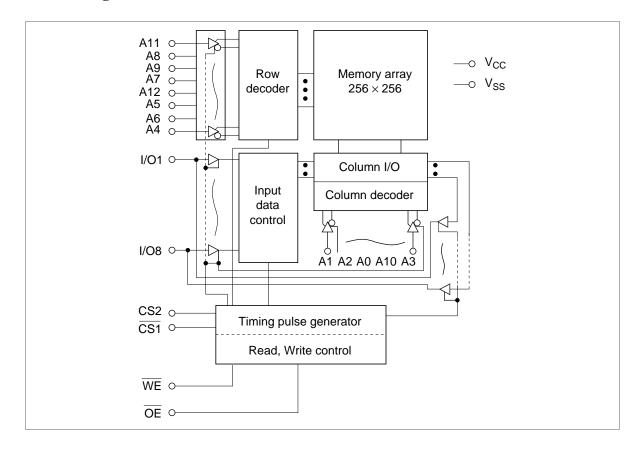
Pin Arrangement



Pin Description

Pin name	Function
A0 to A12	Address input
I/O1 to I/O8	Data input/output
CS1	Chip select 1
CS2	Chip select 2
WE	Write enable
ŌĒ	Output enable
NC	No connection
V _{cc}	Power supply
V _{SS}	Ground

Block Diagram



Function Table

WE	CS1	CS2	OE	Mode	V _{cc} current	I/O pin	Ref. cycle
×	Н	×	×	Not selected (power down)	I_{SB}, I_{SB1}	High-Z	_
×	×	L	×	Not selected (power down)	I_{SB}, I_{SB1}	High-Z	_
Н	L	Н	Н	Output disable	I _{cc}	High-Z	_
Н	L	Н	L	Read	I _{cc}	Dout	Read cycle (1)–(3)
L	L	Н	Н	Write	I _{cc}	Din	Write cycle (1)
L	L	Н	L	Write	I _{cc}	Din	Write cycle (2)

Note: x: H or L

Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Power supply voltage*1	V _{cc}	-0.5 to +7.0	V
Terminal voltage*1	V _T	-0.5^{*2} to V_{CC} + 0.3^{*3}	V
Power dissipation	P _T	1.0	W
Operating temperature	Topr	-40 to +85	°C
Storage temperature	Tstg	-55 to +125	°C
Storage temperature under bias	Tbias	-40 to +85	°C

Notes: 1. Relative to V_{ss}

2. V_T min: -3.0 V for pulse half-width ≤ 50 ns

3. Maximum voltage is 7.0 V

Recommended DC Operating Conditions ($Ta = -40 \text{ to } +85^{\circ}\text{C}$)

Parameter	Symbol	Min	Тур	Max	Unit
Supply voltage	V _{cc}	4.5	5.0	5.5	V
	V _{SS}	0	0	0	V
Input high voltage	V _{IH}	2.4	_	V _{cc} + 0.3	V
Input low voltage	V _{IL}	-0.3* ¹	_	0.6	V

Note: 1. V_{IL} min: -3.0 V for pulse half-width ≤ 50 ns

DC Characteristics (Ta = -40 to +85°C, $V_{CC} = 5$ V $\pm 10\%$, $V_{SS} = 0$ V)

Parameter	Symbol	Min	Typ*1	Max	Unit	Test conditions
Input leakage current	I _{LI}	_	_	2	μΑ	$Vin = V_{SS}$ to V_{CC}
Output leakage current	I _{LO}	_	_	2	μΑ	$\overline{\text{CS1}} = \text{V}_{\text{IH}} \text{ or } \text{CS2} = \text{V}_{\text{IL}} \text{ or } \overline{\text{OE}} = \text{V}_{\text{IH}} \text{ or } \overline{\text{WE}} = \text{V}_{\text{IL}}, \text{V}_{\text{I/O}} = \text{V}_{\text{SS}} \text{ to } \text{V}_{\text{CC}}$
Operating power supply current	I _{CCDC}	_	7	20	mA	$\overline{\text{CS1}} = \text{V}_{\text{IL}}, \text{CS2} = \text{V}_{\text{IH}}, \text{I}_{\text{I/O}} = 0 \text{ mA}$ others = $\text{V}_{\text{IH}}/\text{V}_{\text{IL}}$
Average operating power supply current	I _{CC1}	_	30	50	mA	$\label{eq:min_cycle} \frac{\text{Min cycle, duty} = 100\%,}{\text{CS1}} = \text{V}_{\text{IL}}, \text{CS2} = \text{V}_{\text{IH}}, \text{I}_{\text{I/O}} = 0 \text{ mA} \\ \text{others} = \text{V}_{\text{IH}}/\text{V}_{\text{IL}}$
	I _{CC2}	_	3	8	mA	$\begin{split} & \frac{\text{Cycle time}}{\text{CS1}} = 1 \mu\text{s}, \text{duty} = 100\%, I_{\text{I/O}} = 0 \text{mA} \\ & \frac{\text{CS1}}{\text{CS}} \leq 0.2 \text{V}, \text{CS2} \geq \text{V}_{\text{CC}} - 0.2 \text{V}, \\ & \text{V}_{\text{IH}} \geq \text{V}_{\text{CC}} - 0.2 \text{V}, \text{V}_{\text{IL}} \leq 0.2 \text{V} \end{split}$
Standby power supply current	I _{SB}	_	1	3	mA	$\overline{\text{CS1}} = \text{V}_{\text{IH}}, \text{CS2} = \text{V}_{\text{IL}}$
	I _{SB1} *2		2	200	μΑ	
Output low voltage	V _{OL}	_	_	0.4	V	I _{OL} = 2.1 mA
Output high voltage	V _{OH}	2.4	_	_	V	$I_{OH} = -1.0 \text{ mA}$

Notes: 1. Typical values are at $V_{CC} = 5.0 \text{ V}$, $Ta = +25^{\circ}\text{C}$ and not guaranteed.

2. $V_{IL} \min = -0.3V$

Capacitance (Ta = 25°C, f = 1.0 MHz)

Parameter	Symbol	Min	Тур	Max	Unit	Test conditions
Input capacitance*1	Cin	_	_	5	pF	Vin = 0 V
Input/output capacitance*1	C _{I/O}	_	_	7	pF	V _{I/O} = 0 V

Note: 1. This parameter is sampled and not 100% tested.

AC Characteristics (Ta = -40 to +85 °C, V_{CC} = 5 V \pm 10%, unless otherwise noted.)

Test Conditions

• Input pulse levels: 0.6 V to 2.4 V

Input and output timing reference level: 1.5 V

• Input rise and fall time: 10 ns

• Output load: 1 TTL Gate + C_L (100 pF) (Including scope & jig)

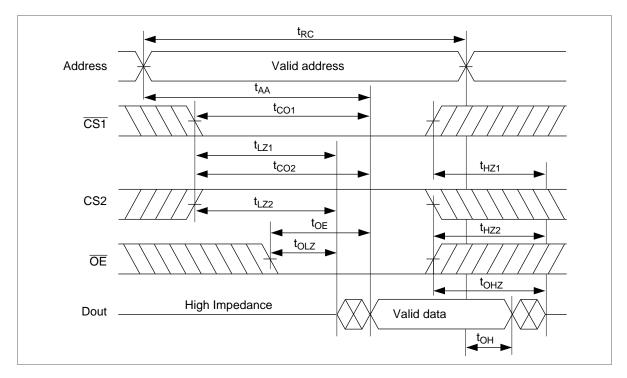
Read Cycle

			HM6264BI-10		HM6264BI-12			
Parameter		Symbol	Min	Max	Min	Max	Unit	Notes
Read cycle time		t _{RC}	100	_	120	_	ns	
Address access time		t _{AA}	_	100	_	120	ns	
Chip select access time	CS1	t _{CO1}	_	100	_	120	ns	
	CS2	t _{CO2}	_	100	_	120	ns	
Output enable to output valid		t _{OE}	_	50	_	60	ns	
Chip selection to output in low-Z	CS1	t _{LZ1}	10	_	10	_	ns	2
	CS2	t _{LZ2}	10		10	_	ns	2
Output enable to output in low-Z		t _{OLZ}	5	_	5	_	ns	2
Chip deselection in to output in high-Z	CS1	t _{HZ1}	0	35	0	40	ns	1, 2
	CS2	t _{HZ2}	0	35	0	40	ns	1, 2
Output disable to output in high-Z		t _{OHZ}	0	35	0	40	ns	1, 2
Output hold from address change		t _{oh}	10		10		ns	

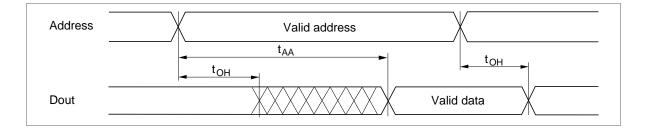
Notes: 1. t_{HZ} is defined as the time at which the outputs achieve the open circuit conditions and are not referred to output voltage levels.

- 2. At any given temperature and voltage condition, t_{HZ} maximum is less than t_{LZ} minimum both for a given device and from device to device.
- 3. Address must be valid prior to or simultaneously with $\overline{CS1}$ going low or CS2 going high.

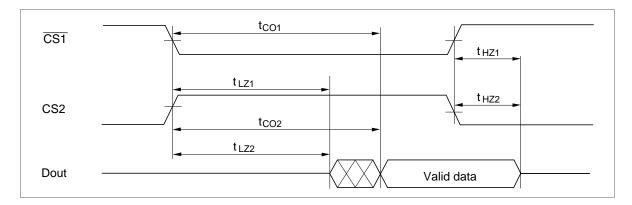
Read Timing Waveform (1) $(\overline{WE}=V_{IH})$



Read Timing Waveform (2) $(\overline{WE}=V_{IH},\,\overline{OE}=V_{IL})$



Read Timing Waveform (3) $(\overline{WE} = V_{IH}, \overline{OE} = V_{IL})^{*3}$



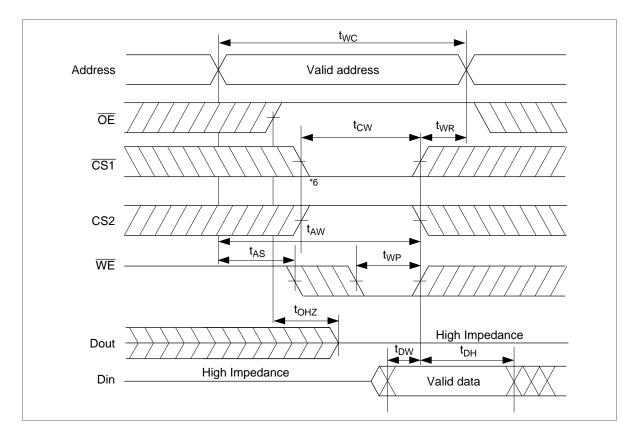
Write Cycle

		HM6264BI-10		HM6264BI-12			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
Write cycle time	t _{wc}	100	_	120	_	ns	
Chip selection to end of write	$t_{\scriptscriptstyle CW}$	80	_	85	_	ns	2
Address setup time	t _{AS}	0	_	0	_	ns	3
Address valid to end of write	t _{AW}	80	_	85	_	ns	
Write pulse width	t _{WP}	60	_	70	_	ns	1, 9
Write recovery time	t _{wR}	0	_	0	_	ns	4
WE to output in high-Z	t _{whz}	0	35	0	40	ns	5
Data to write time overlap	t _{DW}	40	_	40	_	ns	
Data hold from write time	t _{DH}	0	_	0	_	ns	
Output active from end of write	t _{ow}	5	_	5	_	ns	
Output disable to output in high-Z	t _{OHZ}	0	35	0	40	ns	5

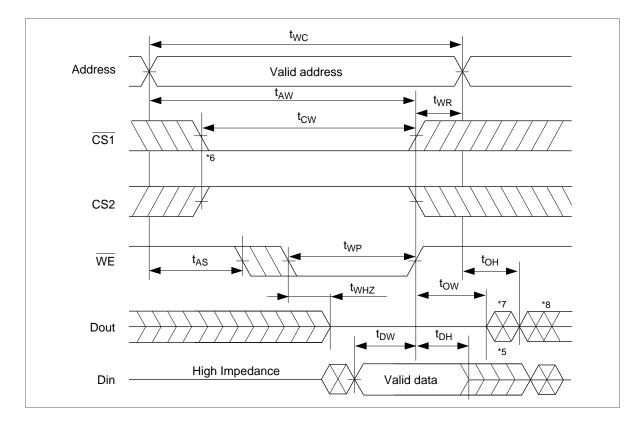
- Notes: 1. A write occurs during the overlap of a low $\overline{CS1}$, and high $\overline{CS2}$, and a high \overline{WE} . A write begins at the latest transition among $\overline{CS1}$ going low, CS2 going high and \overline{WE} going low. A write ends at the earliest transition among $\overline{CS1}$ going high CS2 going low and \overline{WE} going high. Time t_{WP} is measured from the beginning of write to the end of write.
 - 2. t_{cw} is measured from the later of $\overline{CS1}$ going low or CS2 going high to the end of write.
 - 3. $\,t_{\scriptscriptstyle \! AS}$ is measured from the address valid to the beginning of write.
 - 4. t_{WR} is measured from the earliest of $\overline{CS1}$ or \overline{WE} going high or CS2 going low to the end of write cycle.
 - 5. During this period, I/O pins are in the output state, therefore the input signals of the opposite phase to the outputs must not be applied.
 - 6. If CS1 goes low simultaneously with WE going low after WE goes low, the outputs remain in high impedance state.
 - 7. Dout is the same phase of the written data in this write cycle.
 - 8. Dout is the read data of the next address
 - 9. In the write cycle with $\overline{\text{OE}}$ low fixed, t_{WP} must satisfy the following equation to avoid a problem of data bus contention

 $t_{\text{WP}} \geq t_{\text{WHZ}} \; \text{max +} \; t_{\text{DW}} \; \text{min.}$

Write Timing Waveform (1) $(\overline{OE} \operatorname{Clock})$



Write Timing Waveform (2) (\overline{OE} Low Fixed) (\overline{OE} = V_{IL})



11

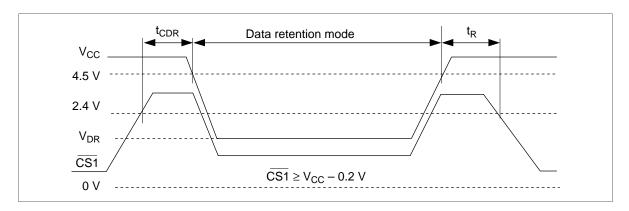
Low V_{CC} **Data Retention Characteristics** (Ta = -40 to +85°C)

Parameter	Symbol	Min	Typ*1	Max	Unit	Test conditions*3
V _{cc} for data retention	V_{DR}	2.0	_	_	V	$\label{eq:cstate} \begin{split} \overline{CS1} &\geq V_{\text{CC}} - 0.2 \text{ V}, \\ \text{CS2} &\geq V_{\text{CC}} - 0.2 \text{ V or CS2} \leq 0.2 \text{ V} \\ \text{Vin} &\geq 0 \text{ V} \end{split}$
Data retention current	I _{CCDR}		1* ¹	100*2	μΑ	
Chip deselect to data retention time	t _{CDR}	0	_	_	ns	See retention waveform
Operation recovery time	t _R	5	_	_	ms	

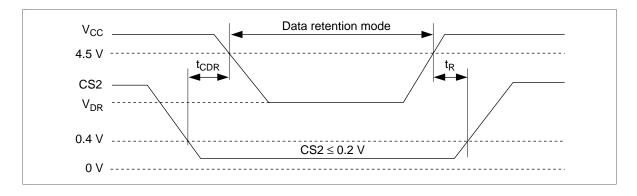
Notes: 1. Reference data at $Ta = 25^{\circ}C$.

- 2. $V_{IL} \min = -0.3V$.
- 3. CS2 controls address buffer, $\overline{\text{WE}}$ buffer, $\overline{\text{CS1}}$ buffer, $\overline{\text{OE}}$ buffer, and Din buffer. If CS2 controls data retention mode, Vin levels (address, $\overline{\text{WE}}$, $\overline{\text{OE}}$, $\overline{\text{CS1}}$, I/O) can be in the high impedance state. If $\overline{\text{CS1}}$ controls data retention mode, CS2 must be $\text{CS2} \ge V_{\text{CC}} 0.2 \, \text{V}$ or $0 \, \text{V} \le \text{CS2} \le 0.2 \, \text{V}$. The other input levels (address, $\overline{\text{WE}}$, $\overline{\text{OE}}$, I/O) can be in the high impedance state.

 $\textbf{Low V}_{CC} \ \textbf{Data Retention Timing Waveform (1)} \ (\overline{CS1} \ Controlled)$



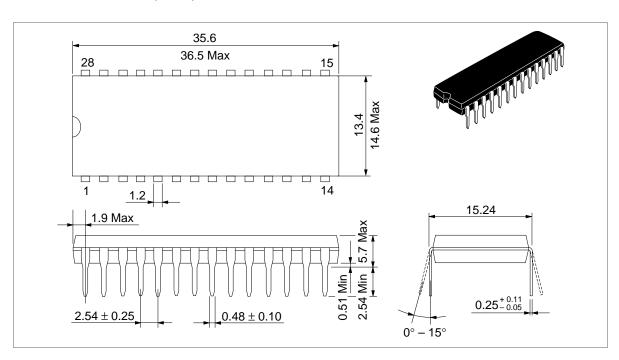
$Low~V_{CC}~Data~Retention~Timing~Waveform~(2)~(CS2~Controlled)\\$



Package Dimensions

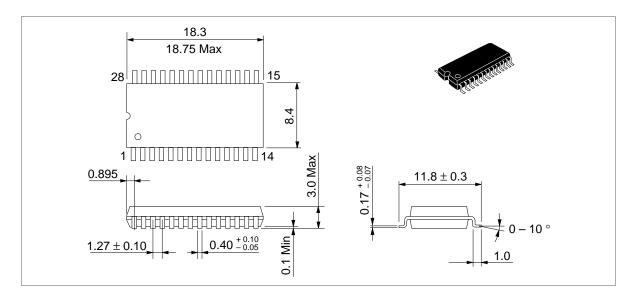
HM6264BLFPI Series (DP-28)

Unit: mm



HM6264BLPI Series (FP-28DA)

Unit: mm



When using this document, keep the following in mind:

- 1. This document may, wholly or partially, be subject to change without notice.
- 2. All rights are reserved: No one is permitted to reproduce or duplicate, in any form, the whole or part of this document without Hitachi's permission.
- 3. Hitachi will not be held responsible for any damage to the user that may result from accidents or any other reasons during operation of the user's unit according to this document.
- 4. Circuitry and other examples described herein are meant merely to indicate the characteristics and performance of Hitachi's semiconductor products. Hitachi assumes no responsibility for any intellectual property claims or other problems that may result from applications based on the examples described herein.1
- 5. No license is granted by implication or otherwise under any patents or other rights of any third party or Hitachi, Ltd.
- 6. MEDICAL APPLICATIONS: Hitachi's products are not authorized for use in MEDICAL APPLICATIONS without the written consent of the appropriate officer of Hitachi's sales company. Such use includes, but is not limited to, use in life support systems. Buyers of Hitachi's products are requested to notify the relevant Hitachi sales offices when planning to use the products in MEDICAL APPLICATIONS.

HITACHI

Hitachi, Ltd.

Semiconductor & IC Div. Nippon Bldg., 2-6-2, Ohte-machi, Chiyoda-ku, Tokyo 100, Japan

Tel: Tokyo (03) 3270-2111 Fax: (03) 3270-5109

For further information write to:

Hitachi America, Ltd. Semiconductor & IC Div. 2000 Sierra Point Parkway Brisbane, CA. 94005-1835 U S A

Tel: 415-589-8300 Fax: 415-583-4207 Hitachi Europe GmbH Electronic Components Group Continental Europe Dornacher Straße 3 D-85622 Feldkirchen München Tel: 089-9 91 80-0

Fax: 089-9 29 30 00

Hitachi Europe Ltd.
Electronic Components Div.
Northern Europe Headquarters
Whitebrook Park
Lower Cookham Road
Maidenhead
Berkshire SL6 8YA
United Kingdom
Tel: 0628-585000
Fax: 0628-778322

Hitachi Asia Pte. Ltd. 16 Collyer Quay #20-00 Hitachi Tower Singapore 0104 Tel: 535-2100 Fax: 535-1533

Hitachi Asia (Hong Kong) Ltd. Unit 706, North Tower, World Finance Centre, Harbour City, Canton Road Tsim Sha Tsui, Kowloon Hong Kong Tel: 27359218 Fax: 27306071

Revision Record

Rev.	Date	Contents of Modification	Drawn by	Approved by
0.0	Dec. 1, 1995	Initial issue	I. Ogiwara	K. Yoshizaki
1.0	Sep. 5, 1996	Deletion of Preliminary		