

§1.9. Absolute stability

Ex. Consider the trapezoidal rule applied to a model problem

$$\begin{cases} u'(t) = \lambda u(t) \\ u(0) = 1 \end{cases}$$

The exact soln is $u(t) = e^{\lambda t}$.

We are interested in the following two cases:

- (i) $\lambda \in \mathbb{R}, \lambda < 0$ } analytic solns asymptotically
- (ii) $\lambda \in \mathbb{C}, \operatorname{Re}(\lambda) < 0$ } converge as $t \rightarrow \infty$.

and we are NOT interested in the following cases:

- (iii) $\lambda \in \mathbb{R}, \lambda > 0$ } analytic solns do NOT
- (iv) $\lambda \in \mathbb{C}, \operatorname{Re}(\lambda) \geq 0$ } asymptotically converge as $t \rightarrow \infty$.

Now consider the trapezoidal method applied to the IVP:

$$\begin{aligned} U^{n+1} &= U^n + \frac{\Delta t}{2} [\lambda U^n + \lambda U^{n+1}] \\ &= U^n + \frac{\lambda \Delta t}{2} [U^n + U^{n+1}] \end{aligned}$$

$$\Rightarrow U^{n+1} \left(1 - \frac{\lambda \Delta t}{2}\right) = U^n \left(1 + \frac{\lambda \Delta t}{2}\right)$$

$$\begin{aligned} \Rightarrow U^{n+1} &= \left(\frac{1 + \frac{\lambda \Delta t}{2}}{1 - \frac{\lambda \Delta t}{2}} \right) U^n \\ &= \dots \\ &= \left(\frac{1 + \frac{\lambda \Delta t}{2}}{1 - \frac{\lambda \Delta t}{2}} \right)^n U^0 \\ &= \underbrace{\left(\frac{1 + \frac{\lambda \Delta t}{2}}{1 - \frac{\lambda \Delta t}{2}} \right)^n}_{= N^n} \quad \text{if } \frac{\lambda \Delta t}{2} \neq 0. \end{aligned}$$

Let $\lambda = a + bi$ with $a < 0$, then

$$|r| = \left| \frac{1 + \frac{\lambda \Delta t}{2}}{1 - \frac{\lambda \Delta t}{2}} \right| = \left| \frac{2 + \lambda \Delta t}{2 - \lambda \Delta t} \right|$$

$$= \frac{\sqrt{(2 + a\Delta t)^2 + (b\Delta t)^2}}{\sqrt{(2 - a\Delta t)^2 + (b\Delta t)^2}}$$

$$< 1, \text{ since } (2 + a\Delta t)^2 < (2 - a\Delta t)^2 \\ \text{when } a < 0.$$

→ We call "r" the amplification (or growth) factor.

→ Since $|r| < 1$, we see that $U^{n+1} \rightarrow 0$ as $n \rightarrow \infty$.

→ the method is stable for all λt .

$$\text{Rmk. } \frac{1 + \frac{\lambda \Delta t}{2}}{1 - \frac{\lambda \Delta t}{2}} \stackrel{\frac{\lambda \Delta t}{2} \neq 1}{=} \left(1 + \frac{\lambda \Delta t}{2}\right) \left(1 + \frac{\lambda \Delta t}{2} + \left(\frac{\lambda \Delta t}{2}\right)^2 + \left(\frac{\lambda \Delta t}{2}\right)^3 + \dots\right)$$

$$= 1 + \lambda \Delta t + \underbrace{\frac{(\lambda \Delta t)^2}{2} + \frac{(\lambda \Delta t)^3}{4} + \dots}_{\text{exact soln}} \\ \sim e^{\lambda \Delta t} \text{ up to } O(\Delta t^2)$$

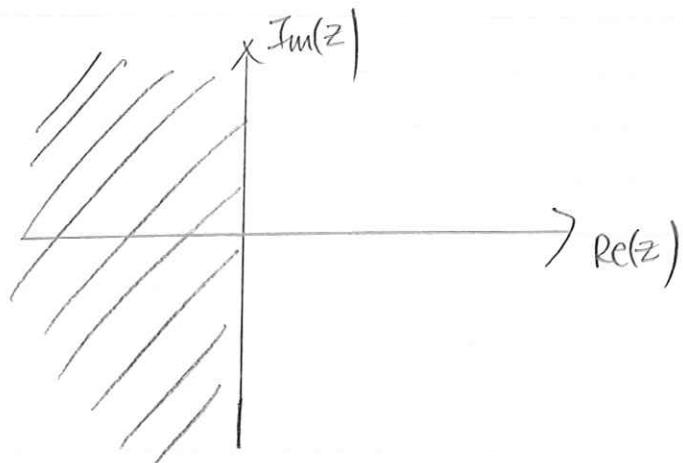
This illustrates again that the method is 2nd-order accurate.

Ruk The stability region for the trapezoidal method can be found if we let

$$z = \lambda + t \in \mathbb{C},$$

As we saw already, the method is stable if $\operatorname{Re}(z) < 0$,

Hence the stability region on \mathbb{C} becomes



If $z \in \mathbb{R}$, then $(-\infty, 0)$.

Ex. Backward Euler (BE)

Again we consider the same IVP.

$$\rightarrow U^{n+1} = U^n + \Delta t \lambda U^{n+1}$$

$$\rightarrow (1 - \lambda \Delta t) U^{n+1} = U^n$$

$$\rightarrow U^{n+1} = \frac{1}{1 - \lambda \Delta t} U^n$$

= ---

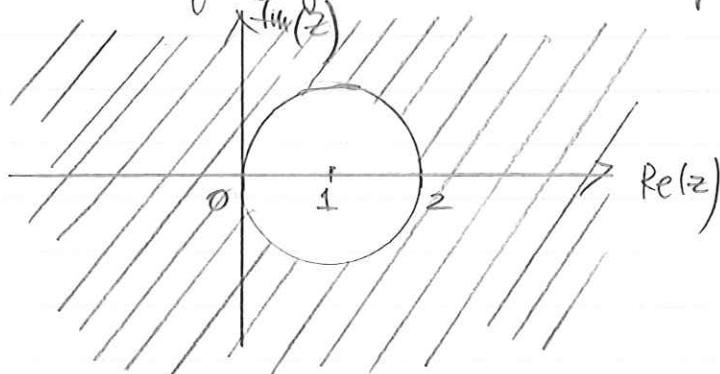
$$= \left(\frac{1}{1 - \lambda \Delta t} \right)^n$$

\rightarrow The method is stable if $\left| \frac{1}{1 - \lambda \Delta t} \right| \leq 1$

$$\rightarrow |1 - \lambda \Delta t| \geq 1 \quad \dots \textcircled{5}$$

\rightarrow If we let $\lambda \in \mathbb{C}$ with $\operatorname{Re}(\lambda) < 0$, and let $z = \lambda \Delta t \in \mathbb{C}$, then

$\textcircled{5}$ is equivalent to $1 \leq |1 - z|$, giving the stability region in a complex plane:



\rightarrow If $\lambda \in \mathbb{R}$, then the stability region becomes $(-\infty, 0)$, with $\lambda < 0$.

Rirk. Again, we see that

$$\frac{1}{1-\lambda\Delta t} = 1 + \lambda\Delta t + (\lambda\Delta t)^2 + \dots$$

$\underbrace{}_{\sim e^{\lambda\Delta t}}$

which agrees to $e^{\lambda\Delta t}$ up to $\mathcal{O}(\Delta t)$,

Hence confirming the method is 1st order.

(FE)

Ex. Now consider the Forward Euler's method applied to the same problem:

$$\begin{cases} u'(t) = \lambda u(t) \\ u(0) = 1 \end{cases} \Rightarrow u(t) = e^{\lambda t}; \text{ exact soln}$$

Again assume $\begin{cases} \lambda < 0 \text{ if } \lambda \in \mathbb{R}, \text{ or} \\ \operatorname{Re}(\lambda) < 0 \text{ if } \lambda \in \mathbb{C}. \end{cases}$

The Forward Euler's method:

$$\begin{aligned} v^{n+1} &= v^n + \Delta t \lambda v^n \\ &= (1 + \lambda \Delta t) v^n \\ &= \dots \\ &= (1 + \lambda \Delta t)^n v^0 \quad (= N^n) \end{aligned}$$

The method is stable if the growth factor:

$$|r| = |1 + \lambda \Delta t| \leq 1, \quad \dots \quad (4)$$

otherwise, it is unstable, although the exact soln is stable.

If $\lambda \in \mathbb{R}$ with $\lambda < 0$, then (4) is equivalent to

$$-2 \leq \lambda \Delta t \leq 0$$

$$\Rightarrow \boxed{0 \leq \Delta t \leq \frac{-2}{\lambda}} \quad (\lambda < 0)$$

\uparrow the stability bound of Δt .

Rmk. Similarly, the growth factor

$$r = 1 + \lambda \Delta t$$

agrees to the exact soln

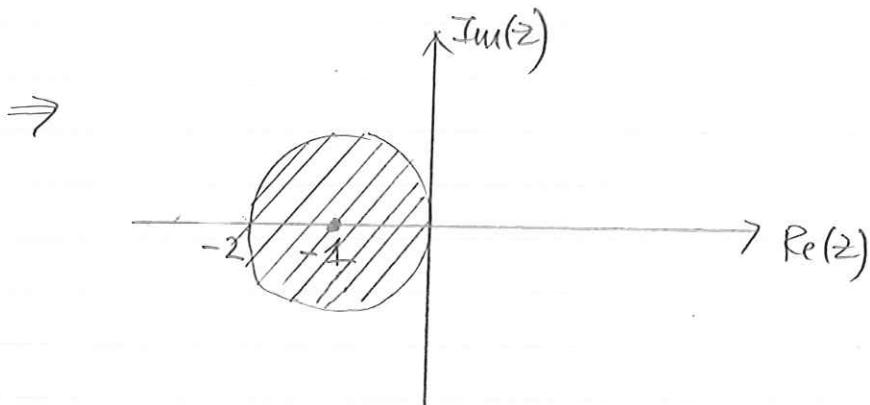
$$e^{\lambda \Delta t} = 1 + \lambda \Delta t + \frac{(\lambda \Delta t)^2}{2} + \frac{(\lambda \Delta t)^3}{3!} + \dots$$

up to $O(\Delta t)$.

→ Thus the method is again 1st-order method.

Rmk. The stability region is, letting $z = \lambda \Delta t$, and from ④,

$$|1+z| \leq 1$$



If $-z \in \mathbb{R}$, then $-2 \leq \lambda \Delta t \leq 0$, $\lambda < 0$,
as we saw before,

Rank.

- (1) For the trapezoidal & BE methods, we see that they are stable for all choices of Δt
→ a property of implicit methods
→ unconditionally stable.
- (2) For FE, there is a condition on Δt for stability
→ a property of explicit methods
→ Conditionally stable.

Def. the region in the complex plane that determines the stability condition on Δt is called the absolute stability region, or simply, stability region.

Rank, Choice of Δt

- The time step Δt must be chosen small enough to allow the local truncation error E_T^{n+1} is small.
- The appropriate step size Δt is different for different methods.
- The size of Δt can make the accuracy of a given method different.
- The size of Δt must be small enough to make the scheme absolutely stable on a given IVP, i.e., we need to choose and check if Δt belongs to the absolute stability region.

Def. An ODE method is said to be A-stable (different from absolute stable) if its region of absolute stability contains the entire left hand plane

$$\{z \in \mathbb{C} \mid \operatorname{Re}(z) \leq 0\}.$$

Ex. Consider the IVP $\begin{cases} u'(t) = \lambda u(t), & \lambda < 0, \\ u(0) = u^0. \end{cases}$

→ ① Trapezoidal method is A-stable →

② Backward Euler method is A-stable →

③ Forward Euler method is NOT A-stable.

Rmk. If Δt is chosen from the absolute stability region, the numerical method and its actual computation U^n becomes $\begin{cases} \text{① stable,} \\ \text{② convergent to a correct soln.} \end{cases}$

Def. The stability poly. Π can be expressed in terms of the char. polynomials g & δ for LMM:

$$\boxed{\Pi(\zeta; z) = g(\zeta) - z\delta(\zeta)}$$

Def. The region of absolute stability for LMM is the set of points $z \in \mathbb{C}$ for which $\Pi(\zeta; z)$ satisfies the root conditn,

i.e., (i) $|\zeta_j| \leq 1$, for distinct roots, $j=1, \dots, r$,

(ii) $|\zeta_n| \neq 1$ if ζ_n is a repeated root of Π .

Ex. Forward Euler's method :

$$U^{n+1} = U^n + \Delta t f(U^n)$$

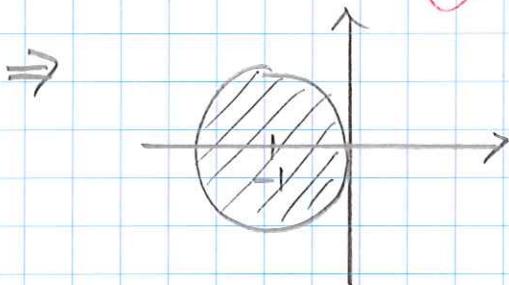
$$\Rightarrow \begin{cases} f(\zeta) = \zeta - 1 \\ \delta(\zeta) = 1 \end{cases}$$

$$\Rightarrow \pi(\zeta; z) = \zeta - 1 - z = \zeta - (1+z).$$

\Rightarrow π has the single root $\zeta_1 = 1+z$.

\Rightarrow The root condition implies to have

$$|\zeta_1| \leq 1 \Leftrightarrow |1+z| \leq 1$$



Ex. Backward Euler's method :

$$U^{n+1} = U^n + \Delta t f(U^{n+1})$$

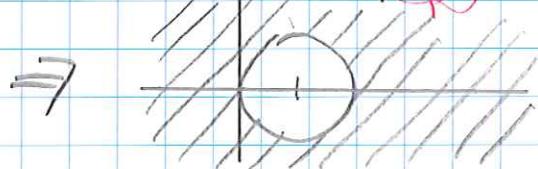
$$\Rightarrow \begin{cases} f(\zeta) = \zeta - 1 \\ \delta(\zeta) = \zeta \end{cases}$$

$$\Rightarrow \pi(\zeta; z) = \zeta - 1 - z\zeta = (1-z)\zeta - 1$$

\Rightarrow π has the single root $\zeta_1 = \frac{1}{1-z}$

\Rightarrow The root condition gives

$$|\zeta_1| \leq 1 \Leftrightarrow |1-z| \geq 1$$



Ex. Trapezoidal method :

$$U^{n+1} - U^n = \frac{\Delta t}{2} [f(U^n) + f(U^{n+1})]$$

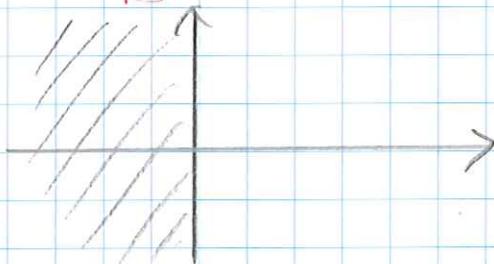
$$\Rightarrow \begin{cases} f(\zeta) = \zeta - 1 \\ g(\zeta) = \frac{1}{2}(\zeta + 1) \end{cases}$$

$$\Rightarrow \pi(\zeta; z) = \zeta - 1 - \frac{z}{2}(\zeta + 1)$$

$$= (1 - \frac{z}{2})\zeta - (1 + \frac{z}{2})$$

$$\Rightarrow \text{The single root } \zeta_1 = \frac{1 + \frac{z}{2}}{1 - \frac{z}{2}}$$

$$\Rightarrow |\zeta_1| \leq 1 \quad \Leftrightarrow \quad \operatorname{Re}(z) \leq 0$$



Ex. Midpoint method :

$$U^{n+2} - U^n = 2\Delta t f(U^{n+1})$$

$$\Rightarrow \begin{cases} f(\zeta) = \zeta^2 - 1 \\ g(\zeta) = 2\zeta \end{cases}$$

$$\Rightarrow \pi(\zeta; z) = (\zeta^2 - 1) - z(2\zeta) = \zeta^2 - 2z\zeta - 1$$

$$\Rightarrow \zeta_{1,2} = z \pm \sqrt{z^2 + 1}$$

\Rightarrow If $z = xi$ with $|x| < 1$, then $|\zeta_1| = |\zeta_2| = 1, \zeta_1 \neq \zeta_2$,
the root condition is satisfied. \checkmark

\Rightarrow Otherwise, the root condition is NOT satisfied,
for example, if $z = \pm i$, then $\zeta_1 = \zeta_2$, a repeated
root with $|\zeta_1| = |\zeta_2| = 1$. (\times)